| **AP CSP Python with Robots****Mission 7 Obj 10-11 Assignment** | **Name:** |
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| **Mission 7 Introduction** |
| Read the introduction and project goals. During this assignment, you will complete the last goal. |
| **Mission 7 Objectives 10-11** |
| Complete Objective 10. Define a constant for SPEED and use it in the main program. Your code for turning does not have to be the same as CodeTrek. | *You already have a branch in the selection block for going straight. Just modify your existing code to use the constant SPEED.**You do not need to rearrange the branches of your selection block.* |
| Complete Objective 11. CodeTrek will show you another way to define the drive() function. Make sure to follow all the instructions, even below the last step to reset n\_sample and target. | *You will delete the current if statement block and replace it with the code for n\_sample.**Start with a much slower speed than 50, like 20.* |
| After Objective 11, submit your completed ***HotPursuit*** program to the teacher. |